

Rarefaction waves

$$u_t + f(u)_x = 0$$

$$u \in \mathbb{R}^n$$

$$f \in \mathbb{R}^n$$

Assume system is strictly hyperbolic, i.e. $df(u)$ has n distinct real e.v.

Note that the equation is scale invariant, i.e. if u is a solution, then also

$$v = v(x,t) = u(hx, ht) \quad h \text{ const.}$$

will be a solution since

$$\begin{aligned} v_t + f(v)_x &= u_t h + df'(u) u_x h \\ &= h(u_t + f(u)_x) = 0 \end{aligned}$$

Then we can assume that

$$u(x,t) = w\left(\frac{x}{t}\right) \quad \xi = \frac{x}{t}$$

Insert this in the equation.

Then:

$$\begin{aligned} 0 &= u_t + f(u)_x = u_t + df(u)u_x \\ &= \dot{w} \left(-\frac{x}{t^2}\right) + df(w) \dot{w} \frac{1}{t} \\ &= \frac{x}{t} \left(df(w) \dot{w} - \frac{x}{t} \dot{w} \right) \end{aligned}$$

or

$$\underline{df(w) \dot{w} = \xi \dot{w}}$$

Scalar case: If $\dot{w} \neq 0$, we get $df(w) = \xi$

and we get $w = (df)^{-1}(\xi)$
which was the formula for rarefaction waves.

In case of systems, we have

$$dF(w) \dot{w} = \zeta \dot{w}$$

$$dF(w) \Gamma_j = \lambda_j \Gamma_j$$

Thus: $\begin{cases} \dot{w} = \Gamma_j(w) \\ \lambda_j(w) = \zeta \end{cases} \leftarrow \text{system of ODEs}$

Consider the Riemann problem

$$u(x,0) = \begin{cases} u_L & x < 0 \\ u_R & x > 0 \end{cases}$$

Then we have the following



$$\underline{w(\lambda_j(u_L)) = u_L}$$

$$\underline{w(\lambda_j(u_R)) = u_R}$$

We have:

$$\lambda_j(w(\xi)) = \xi$$

The derivative w.r.t. ξ :

$$\begin{aligned} \underline{1} &= \frac{d}{d\xi} \xi = \frac{d}{d\xi} \lambda_j(w(\xi)) \\ &= \nabla \lambda_j(w(\xi)) \cdot \dot{w}(\xi) \\ &= \underline{\nabla \lambda_j \cdot r_j(\xi)} \end{aligned}$$

If $\nabla \lambda_j \cdot r_j \neq 0$, say $\nabla \lambda_j \cdot r_j = c(\xi)$

we can define $\tilde{r}_j = \frac{1}{c} r_j$. Then

$$\begin{aligned} \nabla \lambda_j \cdot \tilde{r}_j &= 1 \\ \nabla \lambda_j \cdot r_j &= 1 \\ \nabla \lambda_j \cdot r_j &= 0 \end{aligned}$$

genuinely nonlinear GN
linearly degenerate LD

We will assume that the system V is ^{for each j} either GN or LD for all points in the domain.

For the Euler equations one of the families is LD!

We can summarize what we have found in the following theorem:

Thm 5.6 Assume system is
 strictly hyperbolic in the domain
 $u \in D \subset \mathbb{R}^n$. Consider family j
 and assume this family is
 G_N , and assume that
 $\nabla h_j(u) \cdot r_j(u) = 1$ in D . Let $u_e \in D$
 Then there exists a curve
 $R_j(u_e)$ which emanates from
 u_e s.t. for any $u_r \in R_j(u_e)$
 the solution to the RP

$$u|_{t=0} = \begin{cases} u_e & x < 0 \\ u_r & x > 0 \end{cases}$$

is given by

$$u(x,t) = \begin{cases} u_L, & x < \lambda_j(u_L)t \\ w(\frac{x}{t}), & \lambda_j(u_L)t < x < \lambda_j(u_R)t \\ u_R, & x > \lambda_j(u_R)t \end{cases}$$

where w satisfies:

$$\begin{aligned} \dot{w} &= r_j(w), \quad \lambda_j(w(\cdot)) = \cdot \\ \underline{w(\lambda_j(u_L))} &= u_L \\ \underline{w(\lambda_j(u_R))} &= u_R \end{aligned}$$

Pf. Solve eq'n $\begin{cases} \dot{w} = r_j(w) \\ w(\lambda_j(u_L)) = u_L \end{cases}$

locally. We have $1 = \nabla \lambda_j \cdot r_j$
 which gives $\cdot = \lambda_j(w(\cdot))$
 Denote the orbit of this curve
 as R_j . Along this curve we have
 $w(\lambda_j(u_R)) = u_R$.